

**Please replace the paragraph beginning at page 8, line 25, with the following rewritten paragraph:**

Connecting portion 20 of arm 15 is located over connecting plate 55, is housed inside recess 56, coaxially with axis 23, and is connected to connecting plate 55 by a hinge-and-cam-actuating assembly 58 for moving connecting portion 20 to and from surface 57 along a circular trajectory. More specifically, assembly 58 comprises a hinge/actuating body 59 having a substantially T-shaped longitudinal section, and comprising a hinge pin 60, the outer cylindrical surface of which extends coaxially with axis 23 and through tubular wall 26. Body 59 also comprises a plate 61 integral with one end of hinge pin 60 and located on the opposite side of connecting portion 20 to plate 55. Plate 61 has an annular rib 62 facing connecting portion 20 and fitted to wall 27 of portion 20 with the interposition of a bush 63. Hinge pin 60 engages tubular wall 26 in rotary manner to enable connecting portion 20 to rotate in opposite directions about axis 23 with respect to frame a 53, and has an axial through hole 65 formed along an axis 66 parallel to and eccentric with respect to axis 23, and which is engaged in rotary manner by a hinge pin 67 integral with connecting plate 55 and facing surface 57. Two opposite oscillation-damping bushes 69 [[60]] are interposed between the hinge pin 60 and the hinge pin 67.